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## REMARKS ON FLOYD-HOARE DERIVABILITY

This is an abstract of my paper “Programs and program verification in a general setting” submitted to Theoretical Computer Science.

$\omega$  denotes the set of natural numbers. Let  $X = \{x_i : i \in \omega\}$  be the set of variables,  $L_t$  be the set of classical first order formulas of some type  $t$  (cf. [2]) possibly with free variables (elements of  $X$ ). Let  $L_t^n \subseteq L_t$  be the set of formulas the free variables of which are among  $\{x_i : i < n\}$ , in particular  $L_t^0$  denotes the set of formulas without free variables (the set of sentences). Let  $T \subset L_t^0$  be a consistent theory.

DEFINITION 1. The formula  $\varphi \in L_t^{2n}$  is a *program* if

$$T \vdash \forall x_1 \dots \forall x_n \exists! y_1 \dots \exists! y_n \varphi(x_1, \dots, y_n).$$

In the sequel we shall use vector notations and we write, for example,  $\forall \vec{x} \exists! \vec{y} \varphi(\vec{x}, \vec{y})$  instead of the formula above.

Evidently, our definition of program generalizes the usual notion of flow-chart programs, cf. [3]. Roughly speaking, this definition expresses the fact that if the program uses exactly  $n$  registers (including the statement counter) then their content at some moment determines uniquely the content of the registers at the next moment.

By this definition every program  $\varphi$  defines a function  $p_\varphi$  which assigns  $n$ -tuples to  $n$ -tuples in such a way that  $p_\varphi(\vec{x}) = \vec{y}$  iff  $\varphi(\vec{x}, \vec{y})$ . From now on we identify the programs with these functions and write “let  $p$  be a program”, etc. which means “let  $\varphi$  be a program and denote by  $p$  the function defined by  $\varphi$ ”, The function symbol  $p$  will occur in formulas, but these formulas can evidently be rewritten using  $\varphi$  instead.

Let  $\underline{A}$  be a  $t$ -type model of  $T$ , i.e.  $\underline{A} \models T$ . Let  $A$  be the universe of  $\underline{A}$ , and  $[A]^n$  be the set of  $n$ -tuples of elements of  $A$ .

DEFINITION 2. Let  $p$  be a program,  $\vec{q}_0 = \langle q_0^1, \dots, q_0^n \rangle \in [A]^n$  and  $R \subseteq [A]^n$ .  $R$  is a *run* of the program  $p$  starting from  $\vec{q}_0$  if

- (i):  $\vec{q}_0 \in R$  and  $p(\vec{q}) \in R$  for every  $\vec{q} \in R$
- (ii): for every formula  $\Phi \in L_t^n$ ,  $\underline{A} \models \Phi(\vec{q}_0)$  and  $\underline{A} \models \Phi(\vec{q}) \rightarrow \Phi(p(\vec{q}))$  for every  $\vec{q} \in R$  implies  $\underline{A} \models \Phi(\vec{q})$  for every  $\vec{q} \in R$ .

The  $\vec{q} \in R$  is a *haltingpoint* of  $R$  if  $p(\vec{q}) = \vec{q}$ .

Evidently, this definition of run generalizes the definition of continuous trace in [1] which cannot be formulated in general in the lack of any ordering.

DEFINITION 3. Let  $\varphi_{in}$  and  $\varphi_{out} \in L_t^n$  be arbitrary. The program  $p$  is *partially correct* w.r.t.  $\varphi_{in}$  and  $\varphi_{out}$  denoted by  $\models^{pc} (\varphi_{in}, p, \varphi_{out})$  if for every model  $\underline{A}$  of  $T$  and for every run  $R \subseteq [A]^n$  of  $p$  starting from  $\vec{q}_0 \in R$ ,  $\underline{A} \models \varphi_{in}(\vec{q}_0)$  implies  $\underline{A} \models \varphi_{out}(\vec{q})$  for every halting point  $\vec{q}$  of  $R$ .

DEFINITION 4. Let  $\varphi_{in}$  and  $\varphi_{out}$  as above. The program  $p$  is Floyd-Hoare derivable w.r.t.  $\varphi_{in}$  and  $\varphi_{out}$  (Denoted by  $\vdash^{FH} (\varphi_{in}, p, \varphi_{out})$ ) if there exists a formula  $p \in L_t^n$  such that

$$\begin{aligned} T &\vdash \forall \vec{x} (\varphi_{in}(\vec{x}) \rightarrow \Phi(\vec{x})) \\ T &\vdash \forall x (\Phi(\vec{x}) \rightarrow \Phi(p(\vec{x}))) \\ T &\vdash \forall x (\Phi(\vec{x}) \ \& \ p(\vec{x}) = \vec{x} \rightarrow \varphi_{out}(\vec{x})) \end{aligned}$$

THEOREM 1. For every theory  $T$ , every program  $p$  and every formula  $\varphi_{in}$  and  $\varphi_{out}$

$$\models^{pc} (\varphi_{in}, p, \varphi_{out}) \text{ iff } \vdash^{FH} (\varphi_{in}, p, \varphi_{out}).$$

Let  $PA$  consist of the Peano axioms ([2], p. 41). In [1] this theorem was proved in that special case when  $PA \subset T$  (and of course, the type  $t$  contains the type of arithmetic). The following theorem tells why the Peano axioms have played such a distinguished role previously.

THEOREM 2. Suppose the type  $t$  contains the type of arithmetic and  $PA \subset T$ . Let  $p$  be a program,  $R \subseteq [A]^n$  be a run of  $p$  starting from  $\vec{q}_0$  in the model  $\underline{A}$  of  $T$ . Then the halting points of  $R$  have the same type. (I.e. if  $\vec{q}, \vec{r} \in R$  are halting points then for every  $\psi \in L_t^n$ ,  $\underline{A} \models \psi(\vec{q}) \leftrightarrow \psi(\vec{r})$ .) Moreover if we have a formula  $\varphi_0 \in L_t^n$  such that  $T \vdash \exists! \vec{x} \varphi_0(\vec{x})$  and  $\underline{A} \models \varphi_0(\vec{q}_0)$  then  $R$  has at most one halting point.

Finally we give an example (without proof) for a run which has two

halting points of different type. Let the type  $t$  consist of “ $+, S, O, \tau$ ” with arities “ $2, 1, 0, 0$ ” (i.e.  $t$  is the type of additive number theory, cf. [2], p. 43 with a new constant symbol) and let  $T = PA \cap L_t^0$  (i.e. just the axioms of  $PA$  which does not contain the symbol “ $\cdot$ ”). The program  $p$  operates on pairs and is defined by

$$p(x, y) = \begin{cases} (x - 2y - 1, y + 1) & \text{if } x - 2y - 1 \geq 0 \\ (x, y) & \text{otherwise.} \end{cases}$$

It is trivial that  $p$  is a program in  $T$ . Now let  $\underline{A}$  be any non-standard model of  $PA$ , and  $a \in A$  be divisible by every standard element. We interpret  $\tau$  as to be  $a^2$ , this gives a  $t$ -type model for  $T$ . Let

$$R = \{(2ia + a - i^2, a - i) : i \in \omega\} \cup \{(2ia - i^2, a - i) : 0 \leq i \leq a\}.$$

We claim that  $R$  is the wanted run. It starts from the pair  $(a^2, 0)$  which is defined uniquely by the formula  $(x = \tau \ \& \ y = 0) \in L_t^2$ , and it has two halting points, namely  $(a, a)$  and  $(0, a)$ .

## References

- [1] H. Andr  ka and I. N  meti, *Completeness of Floyd Logic*, **Bulletin of the Section of Logic**, Vol. 7 (1978), pp. 115–120.
- [2] C. C. Chang and H. J. Keisler, **Model theory**, North Holland, 1973.
- [3] Z. Mann, **Mathematical theory of computation**, McGraw Hill, 1974.

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