

Alan Chang (WashU): Prescribed projections and efficient coverings by curves in the plane

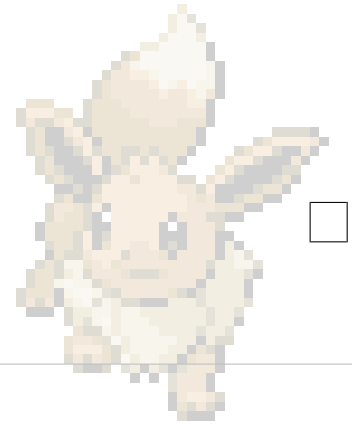
Theorem 1 (Existence of Kakeya sets)

\exists a set $K \subset \mathbb{R}^2$ which is a *union of lines* s.t. (1) K contains a line in every direction and (2) $\mathcal{L}^2(K) = 0$.

Theorem 2 (Dual formulation, a set with one large projection and many small projections)

\exists a set $E \subset \mathbb{R}^2$ s.t. (1) $\text{proj}_0 E \supset [0, 1]$ and (2) for a.e. $\theta \in [0, \pi)$, $\mathcal{L}^1(\text{proj}_\theta E) = 0$.

Proof of Theorem 1 from Theorem 2. Let $K = \bigcup_{(a,b) \in E} \{(x, y) \in \mathbb{R}^2 : y = ax + b\}$. □



Theorem 3 (Davies's efficient covering theorem)

\forall (measurable) $A \subset \mathbb{R}^2$, \exists a set $K \subset \mathbb{R}^2$ which is a *union of lines* s.t. (1) $K \supset A$ and (2) $\mathcal{L}^2(K \setminus A) = 0$.

Theorem 4 (Falconer's digital sundial theorem, a.k.a. Falconer's prescribed projection theorem)

Let $(A_\theta)_{\theta \in [0, \pi)}$ be a collection of subsets of \mathbb{R} (such that $\bigcup_{\theta \in [0, \pi)} (\{\theta\} \times A_\theta)$ is measurable). Then \exists a set $E \subset \mathbb{R}^2$ s.t. (1) $\forall \theta \in [0, \pi)$, $\text{proj}_\theta E \supset A_\theta$ and (2) for a.e. $\theta \in [0, \pi)$, $\mathcal{L}^1((\text{proj}_\theta E) \setminus A_\theta) = 0$.

Theorem 5 (A nonlinear variant of Davies's theorem, AC , Alex McDonald , Krystal Taylor)




Let $\Gamma \subset \mathbb{R}^2$ be the graph of a strictly convex \mathcal{C}^2 function $[a, b] \rightarrow \mathbb{R}$. Then \forall measurable $A \subset \mathbb{R}^2$, \exists a set $K \subset \mathbb{R}^2$ which is a *union of translates of Γ* s.t. (1) $K \supset A$ and (2) $\mathcal{L}^2(K \setminus A) = 0$.

Venetian blinds, digital sundials, and efficient coverings

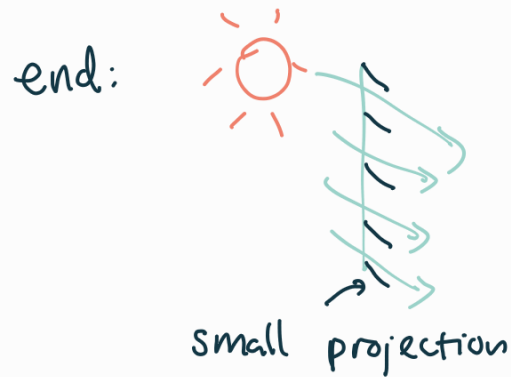
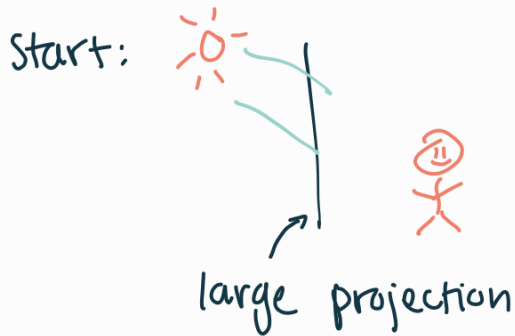
Alan Chang. Washington University in St. Louis.



SSRA 46. "The Promised Land symposium". Łódź, Poland. June 17, 2024.

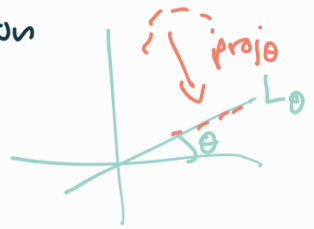
Theorem 5 (A nonlinear variant of Davies's theorem, AC , Alex McDonald , Krystal Taylor )
Let $\Gamma \subset \mathbb{R}^2$ be the graph of a strictly convex C^2 function $[a, b] \rightarrow \mathbb{R}$. Then \forall measurable $A \subset \mathbb{R}^2$, \exists a set $K \subset \mathbb{R}^2$ which is a *union of translates of Γ* s.t. (1) $K \supset A$ and (2) $\mathcal{L}^2(K \setminus A) = 0$.

Venetian blind construction:



We can use Venetian blinds to prove:

Thm 2: $\exists E \subset \mathbb{R}^2$ s.t. (1) $\text{proj}_0 E > [0, 1]$
(2) for a.e. $\theta \in (0, \pi)$, $|\text{proj}_\theta E| = 0$



Idea of pf:



Step 2:



step 3:



Keep iterating. we end up with:

lem: $\forall \varepsilon > 0 \quad \exists E \subset \mathbb{R}^2 \quad \text{s.t.} \quad (1) \text{proj}_0 E \supset [0,1]$

(2) $\forall \theta \notin (-\varepsilon, \varepsilon) \quad |\text{proj}_\theta E| \lesssim \varepsilon$

Repeat this, let $\varepsilon \rightarrow 0$ to get

Thm 2: $\exists E \subset \mathbb{R}^2 \quad \text{s.t.} \quad (1) \text{proj}_0 E \supset [0,1] \quad (2) \forall \theta \neq 0, |\text{proj}_\theta E| = 0$

Thm 1: $\exists K \subset \mathbb{R}^2 \quad \text{s.t.} \quad (1) K \text{ has a line in every direction} \quad (2) \mathcal{L}^2(K) = 0$

pf that Thm 2 \Rightarrow Thm 1: let E be as in Thm 2.

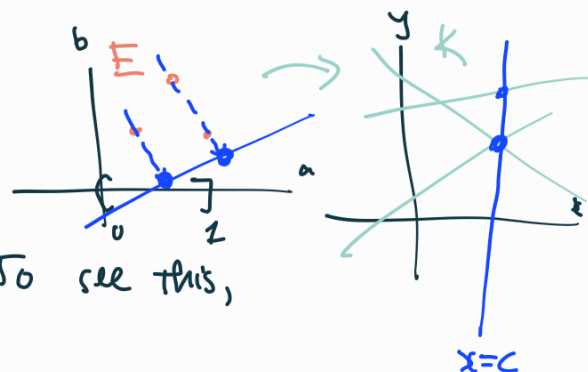
Define $K = \bigcup_{(a,b) \in E} \{(x,y) \in \mathbb{R}^2 : y = ax + b\}$

(1) of Thm 2 \Rightarrow (1) of Thm 1

Also, (2) of Thm 2 \Rightarrow (2) of Thm 1. To see this,

for a.e. $\theta, |\text{proj}_\theta E| = 0$

$\mathcal{L}^2(K) = 0$

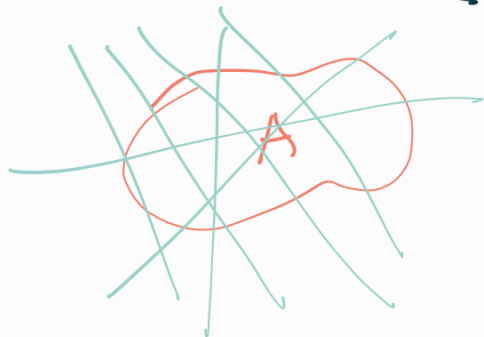


fix $c \in \mathbb{R}$ consider $K \cap \{x=c\}$.

$$\begin{aligned} K \cap \{x=c\} &= \bigcup_{(a,b) \in E} \{(c,y) : y = ac + b\} = \{(c, ac+b) : (a,b) \in E\} \\ &= \{c\} \times \{ac+b : (a,b) \in E\} \end{aligned}$$

This is a proj of E
 $ac+b = (a,b) \cdot (c,1)$

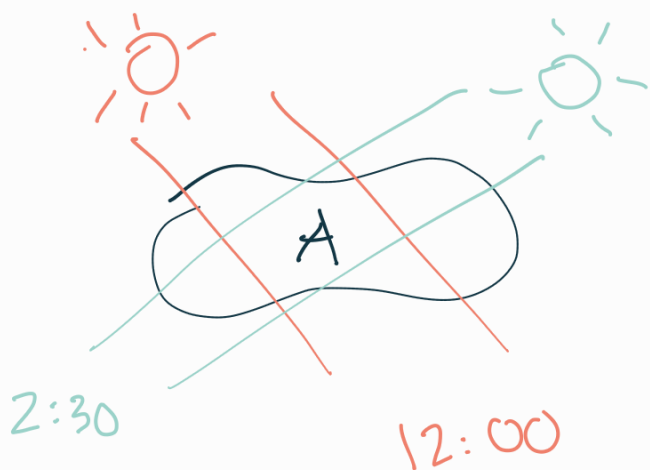
Thm 3: let $A \subset \mathbb{R}^2$. Then $\exists K \subset \mathbb{R}^2$ which is a union of lines
s.t. (1) $K \supset A$ (2) $\mathcal{L}^2(K \setminus A) = 0$.



Note: Thm 1 is actually a special case of Thm 3 if you replace \mathbb{R}^2 with the real projective plane \mathbb{RP}^2 .

Thm 4: let $(A_\theta)_{\theta \in [0,\pi]}$ be subsets of \mathbb{R} . Then $\exists E \subset \mathbb{R}^2$
s.t. (1) $\forall \theta \quad \text{proj}_\theta E \supset A_\theta$. (2) for a.e. $\theta \quad \mathcal{L}^1((\text{proj}_\theta E) \setminus A_\theta) = 0$




"Digital sundial theorem"

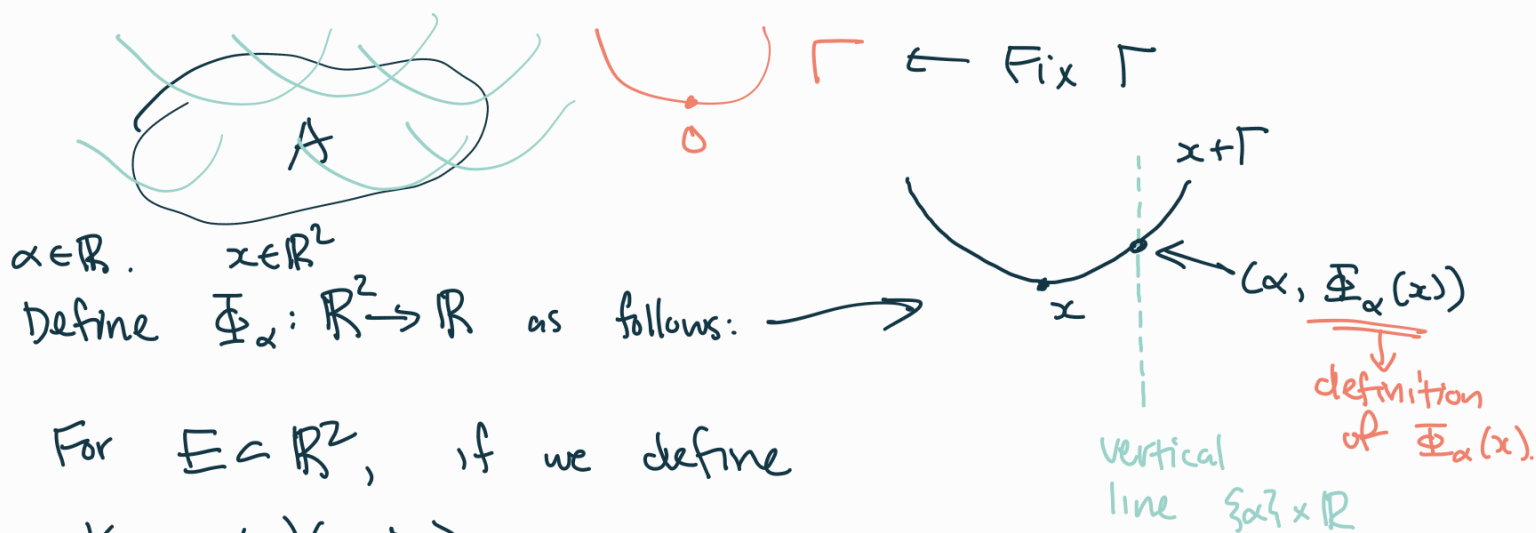


Note: Thm 2 is a special case of Thm 4:

$$\text{let } A_0 = [0, 1] \quad A_\theta = \emptyset \quad \theta \neq 0$$

Thm 4 can be proved using Venetian blinds.

Theorem 5 (A nonlinear variant of Davies's theorem, AC , Alex McDonald , Krystal Taylor )
Let $\Gamma \subset \mathbb{R}^2$ be the graph of a strictly convex \mathcal{C}^2 function $[a, b] \rightarrow \mathbb{R}$. Then \forall measurable $A \subset \mathbb{R}^2$, \exists a set $K \subset \mathbb{R}^2$ which is a union of translates of Γ s.t. (1) $K \supset A$ and (2) $\mathcal{L}^2(K \setminus A) = 0$.



$\alpha \in \mathbb{R}$. $x \in \mathbb{R}^2$
Define $\Phi_\alpha: \mathbb{R}^2 \rightarrow \mathbb{R}$ as follows:

For $E \subset \mathbb{R}^2$, if we define

$$K := \bigcup_{x \in E} (x + \Gamma)$$

$$K \cap (\{\alpha\} \times \mathbb{R}) = \{\alpha\} \times \Phi_\alpha(E)$$

so we want (1) $\forall \alpha \quad \Phi_\alpha(E) \supset A \cap (\{\alpha\} \times \mathbb{R})$
(2) for a.e. α , $|\Phi_\alpha(E)| = 0$

the idea of proving this: " $\{\Phi_\alpha\}_\alpha$ " behave similarly to " $\{\text{proj}_\theta\}_\theta$ " so we can use Venetian blinds

$$\text{proj}_\theta^{-1}(\text{proj}_\theta(x))$$



$$\Phi_\alpha^{-1}(\Phi_\alpha(x))$$

